

LLC Resonant Half Bridge Converter

Asia Tech-Day
August 17 to 27, 2009

Hong Huang
Applications Engineer

Outline

- Introduction to LLC resonant half bridge converter
 - Benefits
 - Operation principle
 - Design challenges
- Design method
 - Transformer turns ratio selection
 - Magnetizing inductor selection
 - Resonant component selection
- Other design issues for LLC resonant converter
 - Current limiting
 - Soft start
 - OVP and Burst Operation

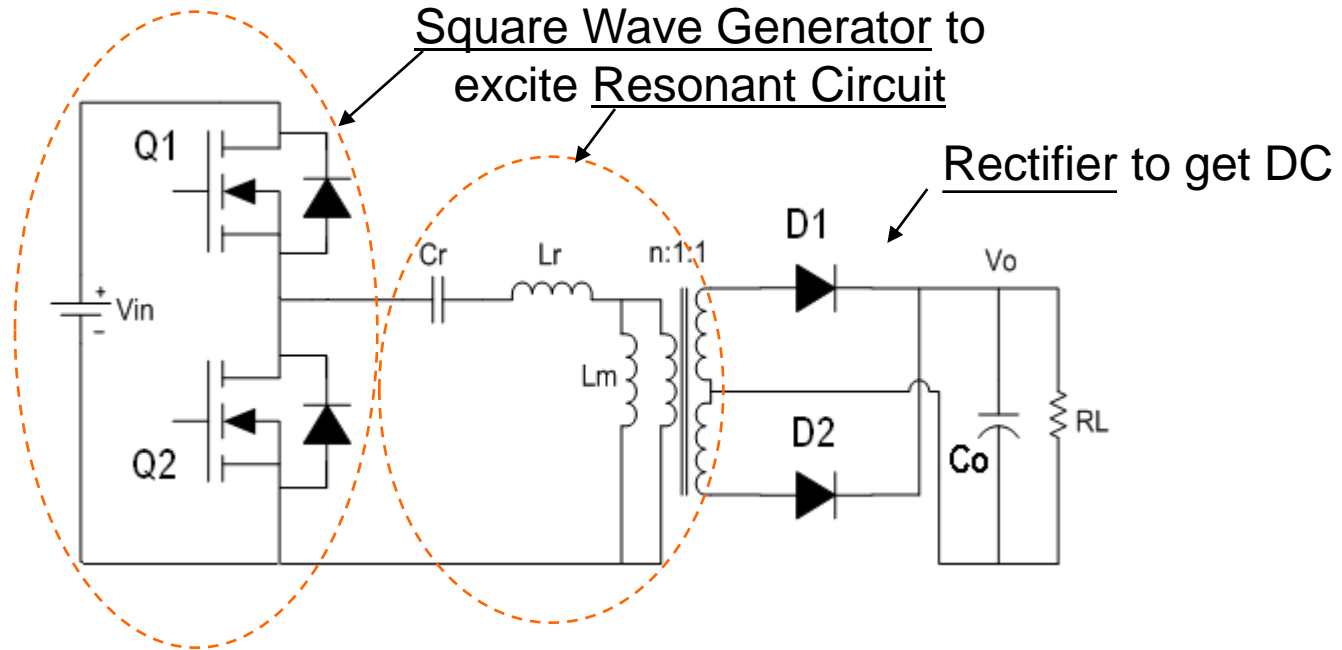
Design Challenges for DC/DC

- Higher power conversion performance
 - Higher efficiency, smaller heat sink
 - Higher switching frequency, smaller magnetics
 - Less energy storage capacitors, smaller size (e.g., for PFC holdup)
 - Moderate frequency variations
- Wide input voltage variations
 - AC-DC applications: holdup time requirement (PFC from 400V to 300V during holdup)
 - Larger Energy Storage Capacitor – high cost, large size, more space
 - Converter ability to tolerate the variations
 - DC-DC applications
 - Telecom, 36 to 75V (32V to 78V)
 - Some applications even asking 4:1 variations
- Wide output voltage trimming

Benefits of LLC Resonant Converter

- ZVS can be achieved by utilizing transformer magnetizing inductor
- Capacitor filter, less voltage stress on rectifiers
- Smaller switching loss due to small turn off current
- Variable switching frequency control, not sensitive to load change
- Frequency variations can be designed narrower compared to SRC
- Wide operation range without reducing normal operation efficiency

LLC Resonant Converter with Wide Operation Range



Resonant frequency

$$f_0 = \frac{1}{2\pi\sqrt{L_r C_r}}$$

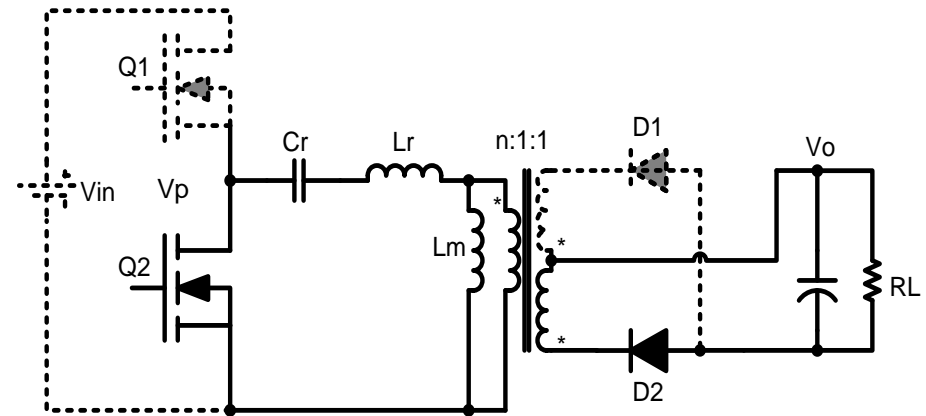
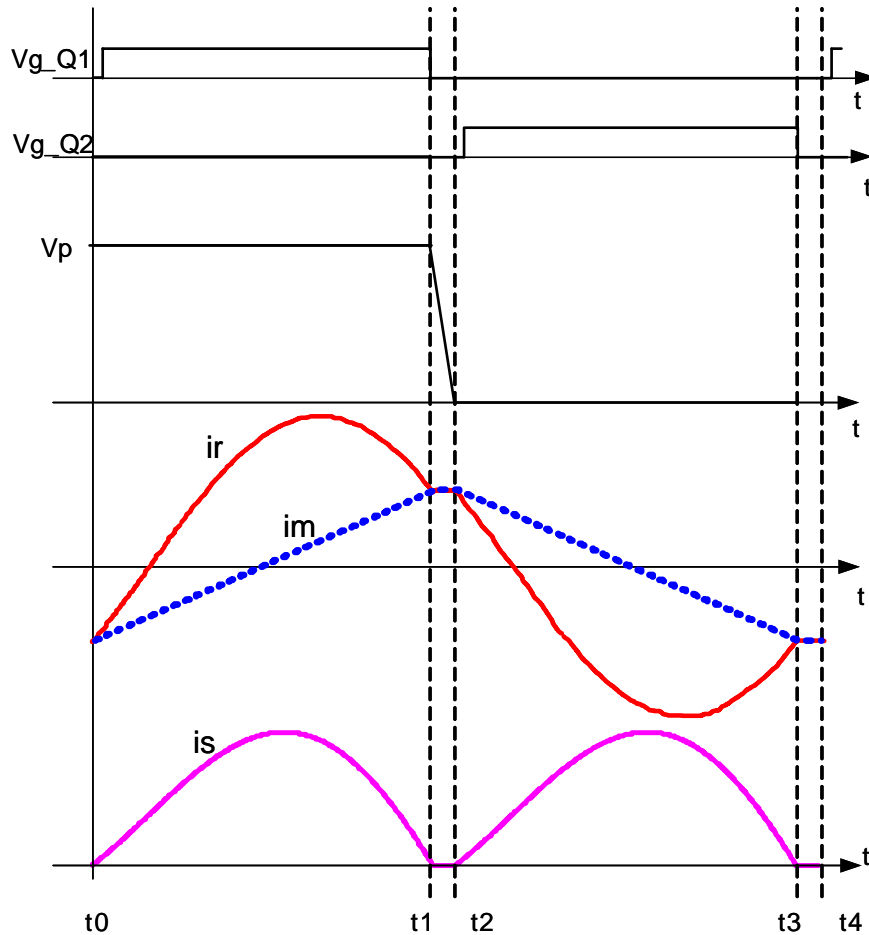
Transformer turns-ratio

$$n = \frac{V_{in}/2}{V_o}$$

- f_{sw} is set at resonant frequency at nominal input and output
- f_{sw} is adjusted by feedback loop at other operation conditions

Operation Principles

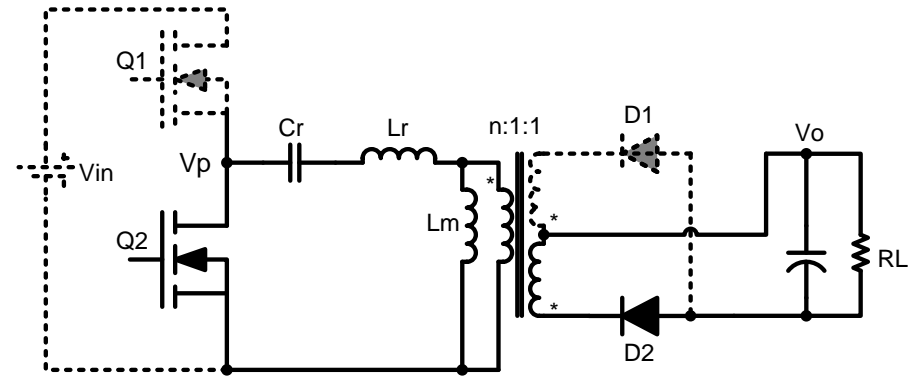
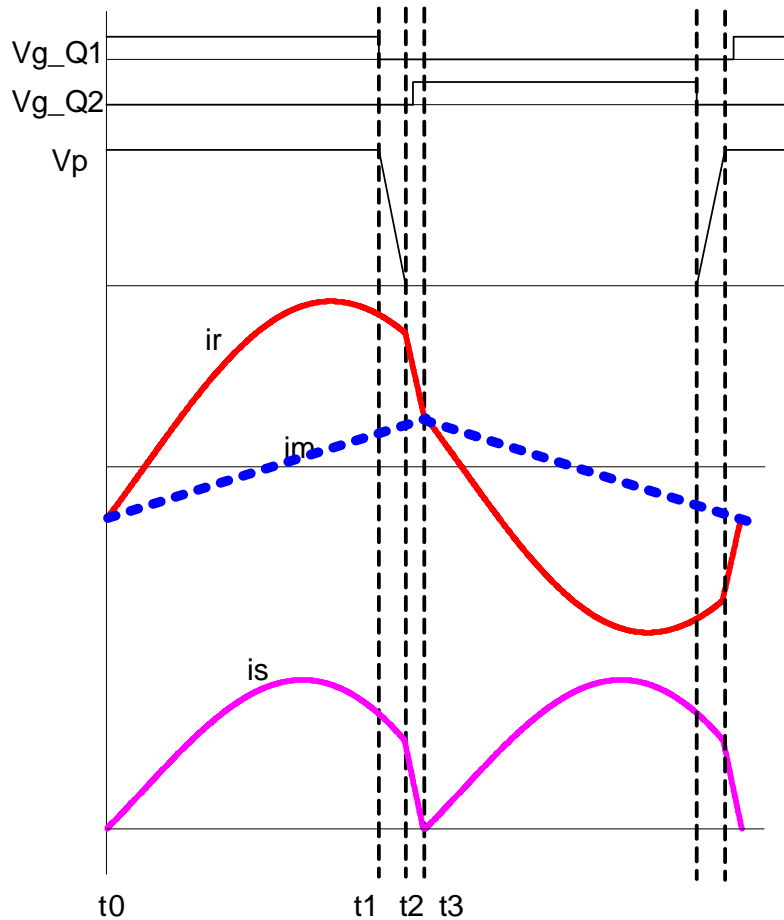
At Resonant Frequency



- $Q2$ and $D2$ ON, $Q1$ and $D1$ OFF
- Magnetizing current in L_m , i_m
- C_r resonates with L_r , i_r
- C_r and L_r deliver energy to output

Operation Principle

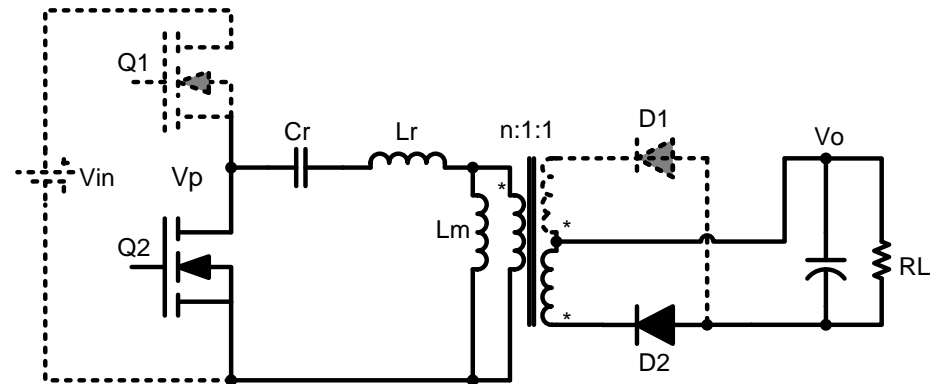
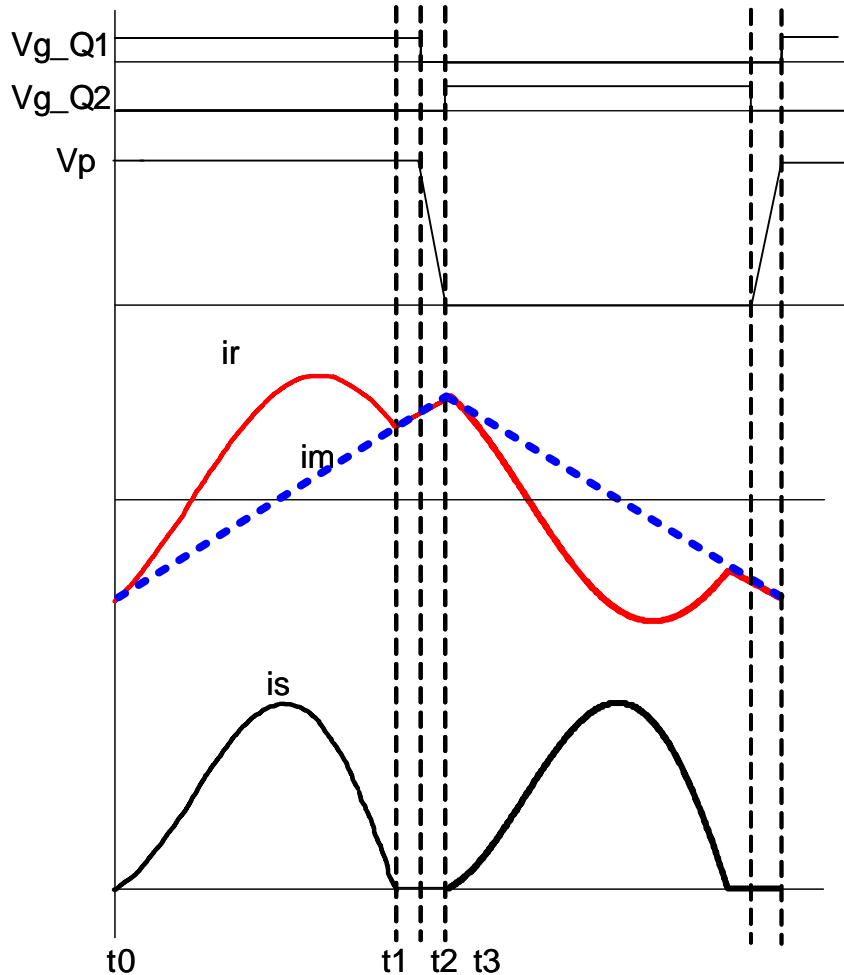
Above Resonant Frequency



- When switching frequency is above resonant frequency, circuit behaves as SRC
- Secondary current becomes CCM, reverse recovery loss increases

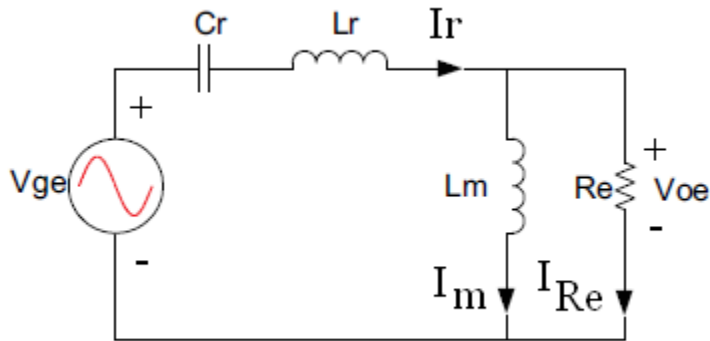
Operation Principle

Below Resonant Frequency



- When switching frequency is below resonant frequency, magnetizing inductor begins to participate in resonant and increases voltage gain
- Secondary diode becomes discontinuous

LLC Resonant Converter Gain Function



$$M = \frac{nV_o}{V_{DC}/2} \approx \frac{V_{oe}}{V_{ge}} = \left| \frac{\frac{j\omega L_m R_e}{j\omega L_m + R_e}}{\frac{j\omega L_m R_e}{j\omega L_m + R_e} + \frac{1}{j\omega C_r} + j\omega L_r} \right|$$

$$V_{oe} = V_{os,1}^{rms} = \frac{2\sqrt{2}}{\pi} nV_o \quad R_e = \frac{8}{\pi^2} n^2 R_L$$

$$I_{Re} = I_{os,1}^{rms} = \left(\frac{\pi}{2\sqrt{2}} I_o \right) / n$$

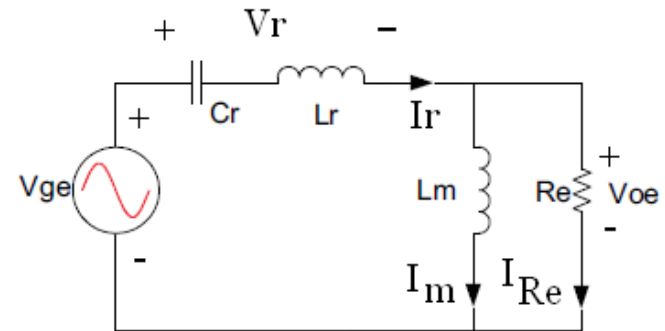


$$M = \left| \frac{L_n f_n^2}{L_n f_n^2 + (f_n^2 - 1)(1 + jf_n L_n Q_e)} \right|$$

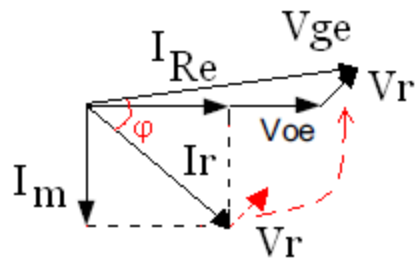
| NORMALIZED GAIN | RESONANT FREQUENCY | QUALITY FACTOR | NORMALIZED FREQUENCY | INDUCTOR RATIO |
|----------------------------|--------------------------------------|------------------------------------|-----------------------|-------------------------|
| $M = \frac{V_o}{V_{DC}/2}$ | $f_0 = \frac{1}{2\pi\sqrt{L_r C_r}}$ | $Q_e = \frac{\sqrt{L_r/C_r}}{R_e}$ | $f_n = \frac{f}{f_0}$ | $L_n = \frac{L_m}{L_r}$ |

LLC Resonant Converter with Wide Operation Range

- Unity gain is reached at $V_r=(V_{Lr}-V_{Cr})=0$, where input voltage is in phase with output voltage, and input voltage applies to load (R_e) directly



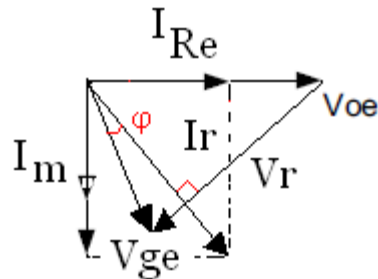
Inductive Region,
 I_r lagging V_{ge}



$$V_r = (V_{Lr} - V_{Cr})$$

$$V_{Lr} > V_{Cr}$$

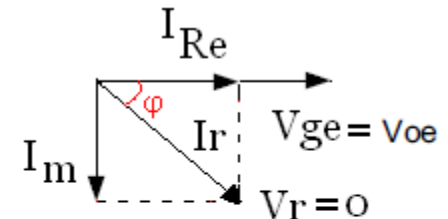
Capacitive Region,
 I_r leading V_{ge}



$$V_r = (V_{Lr} - V_{Cr})$$

$$V_{Lr} < V_{Cr}$$

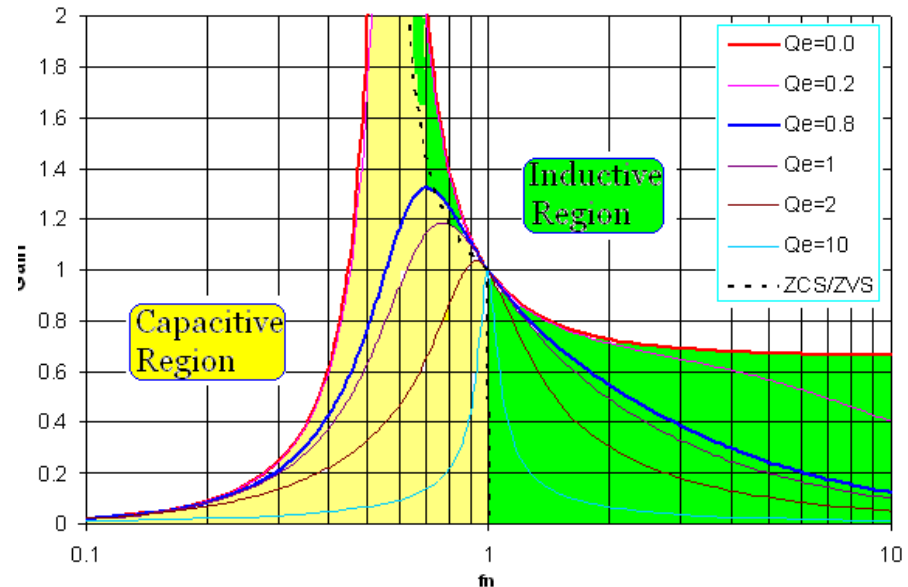
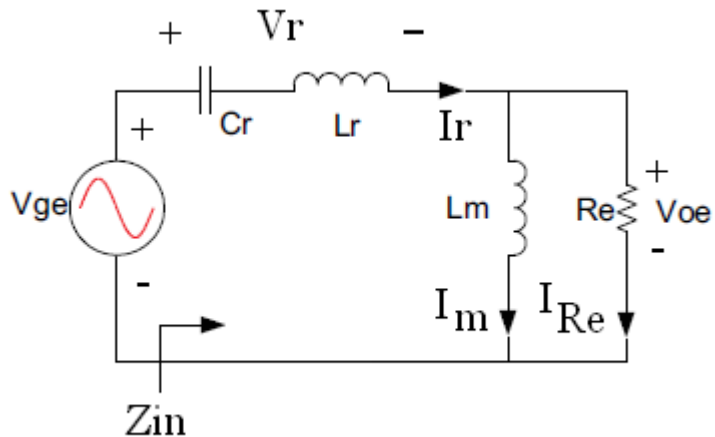
Unity Gain, $V_r=0$
 V_{oe} in phase with V_{ge}



$$V_r = (V_{Lr} - V_{Cr})$$

$$V_{Lr} = V_{Cr}$$

LLC Resonant Converter with Wide Operation Range

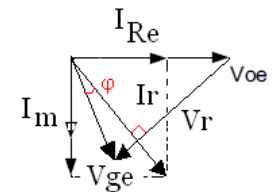


Working regions (Modes)

- Inductive Region, if resonant network current is lagging input voltage
- Capacitive Region, if resonant network current is leading input voltage
- Resistive Region, if resonant network current is in phase with input voltage
(boundary to divide Inductive and capacitive, by let the imaginary part zero of the input impedance)
- Unity gain happens at $(V_{Lr}-V_{Cr})=0$, where input voltage in phase with output voltage, and input voltage applies to load (R_e) directly

LLC Resonant Converter with Wide Operation Range

- Should operate in ZVS region (Inductive Region, I_r lagging V_{ge})
- Avoid ZCS region (Capacitive Region, I_r leading V_{ge})
 - Hard switching of half bridge switches
 - Reverse recovery losses in primary FET body diodes
 - Large spikes on switch node
 - Higher EMI levels
 - Frequency relationship reversed
 - Frequency increases as load increases



$$V_r = (V_{Lr} - V_{Cr})$$

$$V_{Lr} < V_{Cr}$$

Gain Characteristics with Ln and Qe

$$Q_e = \frac{\sqrt{L_r / C_r}}{R_e}$$

Q_e is related to output load

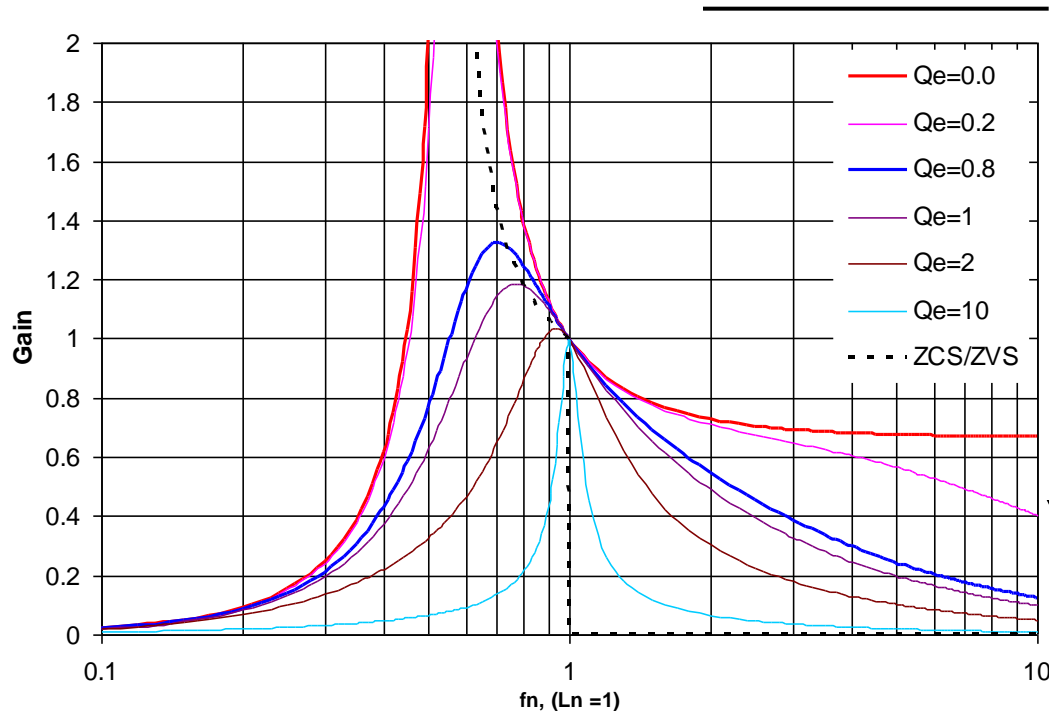
Q_e Increasing with Load Current

$$R_e = \frac{8}{\pi^2} n^2 R_L$$

$$f_0 = \frac{1}{2\pi\sqrt{L_r C_r}}$$

$$f_p = \frac{1}{2\pi\sqrt{(L_r + L_m)C_r}}$$

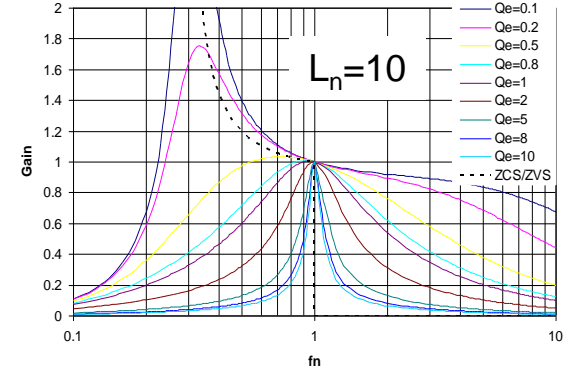
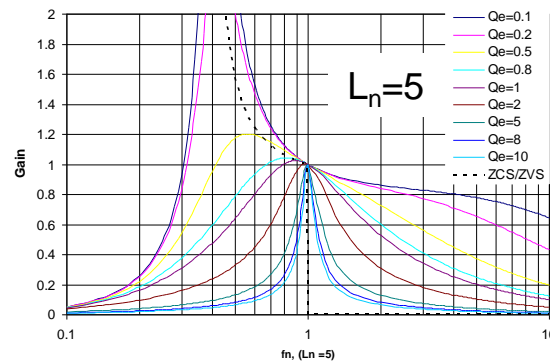
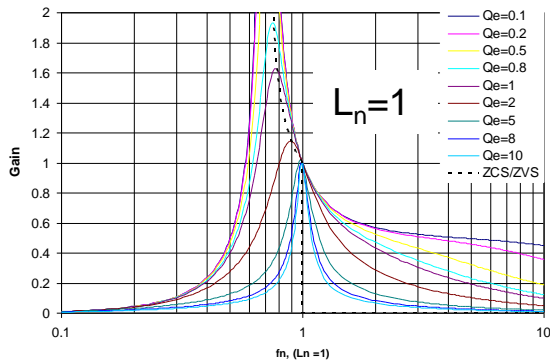
$$f_n = \frac{f}{f_0}$$



Q_e increase with Ln constant (designed L_r , C_r , and operational R_L),

- Peak-gain becomes lower
- Frequency at peak-gain moving to right
- Better "frequency-selective"

Impacts of Circuit Parameters

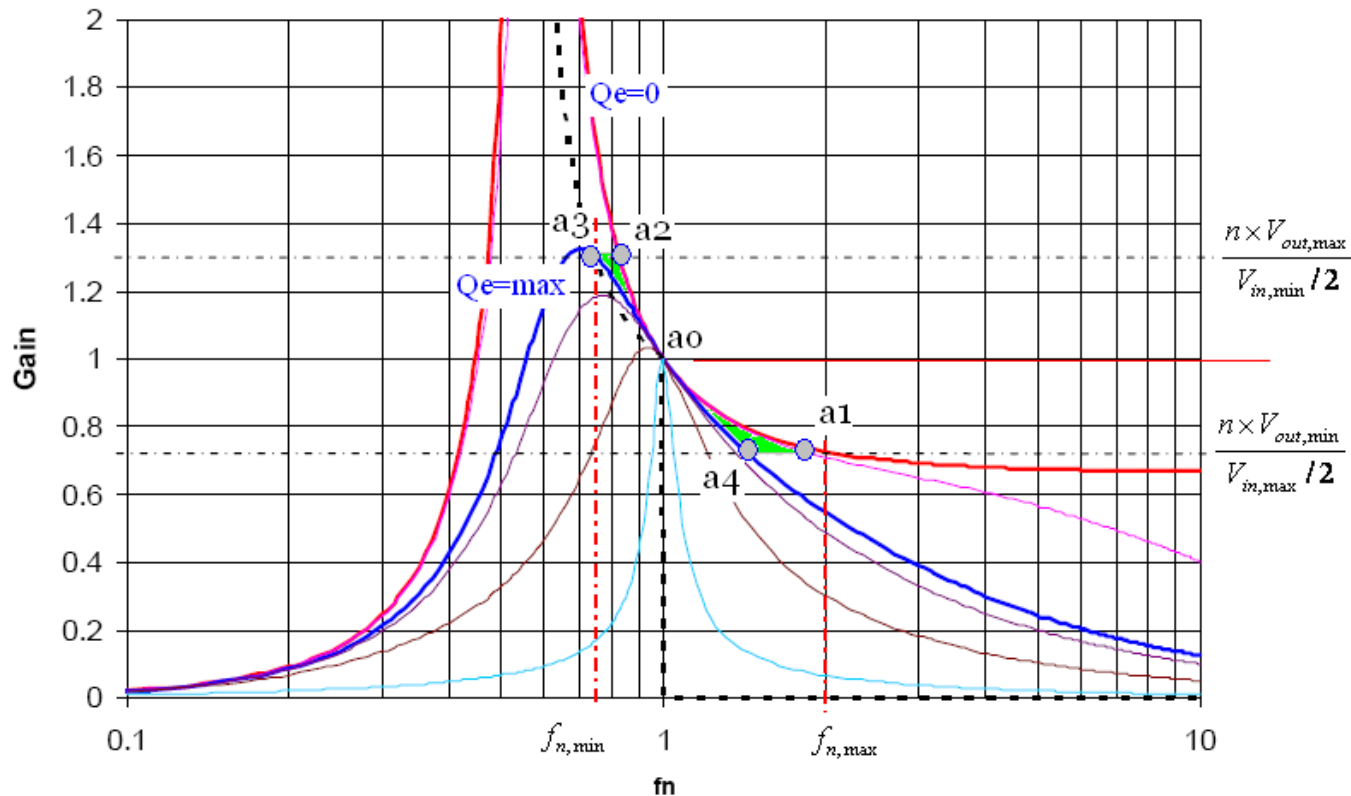


Gain Change with L_n and Q_e

- L_n increase with Q_e constant (designed L_r , C_r , and operational RL),
 - flat,
 - magnitude shift-up,
 - frequency value at peak-gain moving towards more left,
 - less “frequency-selective”
 - wide frequency variation from no load to full load (more discussion later)

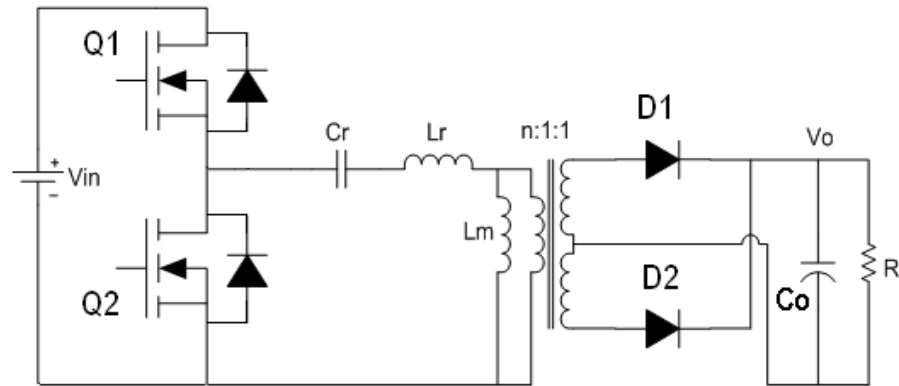
L_n somewhere 3 to 5 look best balance between peak gain and frequency change – can be initially pick-up

LLC Resonant Converter Operation for design consideration



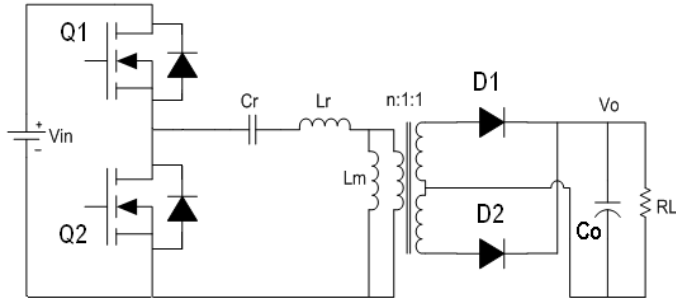
- Operation/design with no load and minimum gain at a1
- Operation /design with full load and maximum gain at a2
- All gain curves cross at unity at $f_n=1$, or $f=f_0$
- Q_e design consideration at Heavy load, OCP, Short Circuit

Design Goals for LLC Resonant Converter



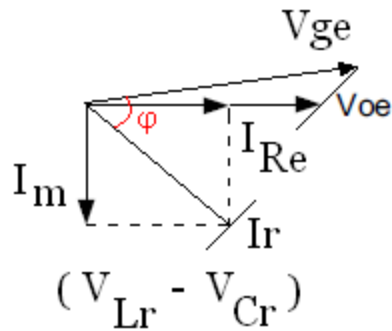
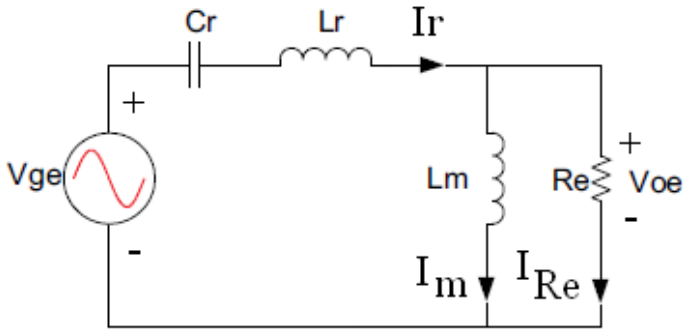
- Minimize RMS current under normal operation condition
- Ensure ZVS operation
- Ensure desired operation range

Design Consideration -1: Primary RMS Current at Normal Operation



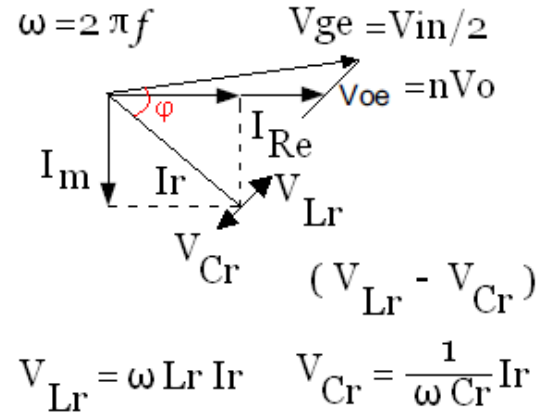
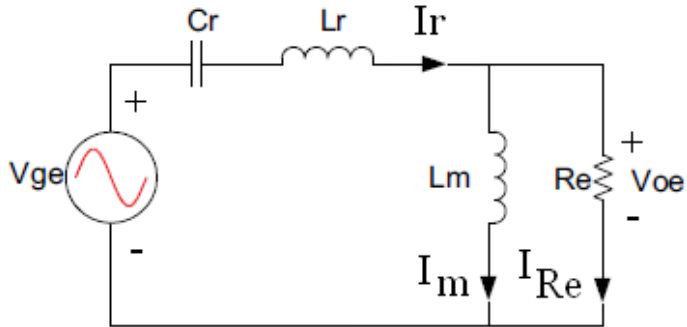
$$I_{P,RMS} = I_r = \sqrt{I_m^2 + I_{Re}^2} =$$

$$FHA \rightarrow \sqrt{\left(\frac{2\sqrt{2} nV_o}{\pi \omega L_m}\right)^2 + \left(\frac{\pi I_o}{2\sqrt{2} n}\right)^2}$$



- Primary current can be easily calculated from the phasor circuit
- Primary side RMS current is summation of magnetizing current and load current
- Larger Lm is better for less conduction losses

Design Consideration -2: Secondary winding RMS Current

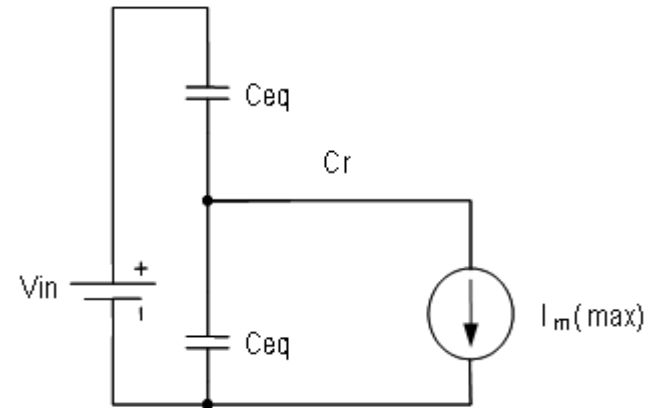
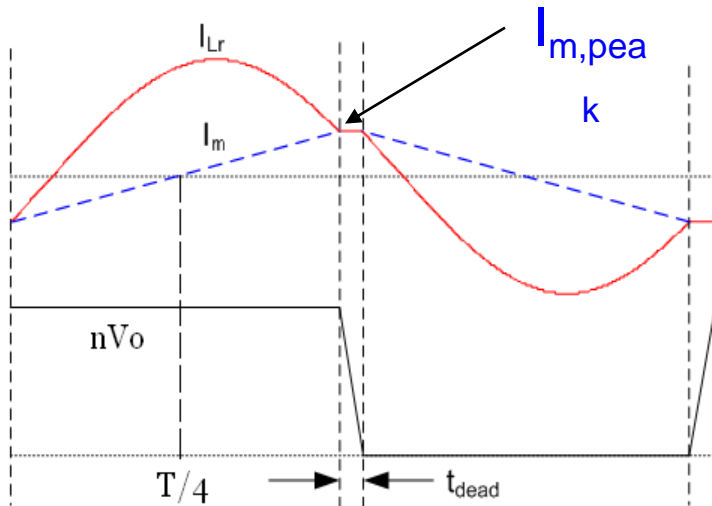


$$I_{RMS_S} = (I_{Re} \times n) / 2 = \frac{\pi}{4\sqrt{2}} I_o \Rightarrow I_{peak_S} = \frac{\pi}{4} I_o, \quad \text{center-tapped}$$

$$I_{RMS_S} = I_{Re} \times n = \frac{\pi}{2\sqrt{2}} I_o \Rightarrow I_{peak_S} = \frac{\pi}{2} I_o, \quad \text{bridge}$$

- Secondary side current is the difference between resonant tank current and magnetizing current

Design Consideration -3: Zero Voltage Switching



$$I_{m,peak} = \frac{nV_o}{L_m} \frac{T}{4}$$

$$\frac{1}{2} (L_m + L_r) I_{m,peak}^2 \geq \frac{1}{2} (2C_{eq}) V_{in}^2$$

$$I_{m,peak} \times t_{dead} \geq 2C_{eq} V_{in}$$

ZVS conditions:

- Enough H-field energy to balance E-field Energy in less than half cycle
- Enough time to make the energy conversion
- Worst operation for ZVS,
 - $V_{o,min}$, $I_{m,peak}$ becomes small
 - $V_{in,max}$, more C_{eq} energy needs to discharge

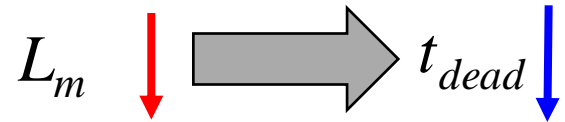
$$L_m \leq \frac{T \times t_{dead}}{16C_{eq}}$$

Trade-off Design of Dead Time



- Smaller turn off current
- Smaller magnetizing current

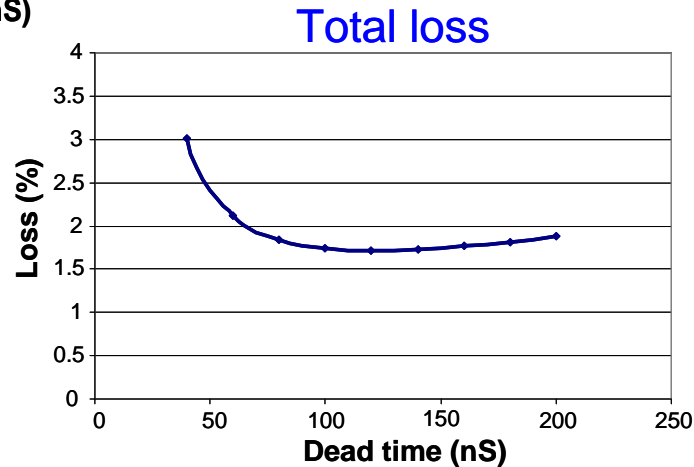
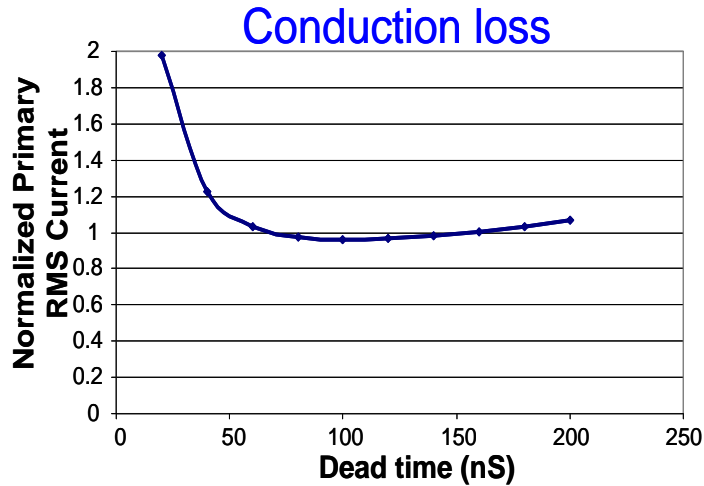
➤ Increase RMS current due to duty cycle loss



- Smaller duty cycle loss

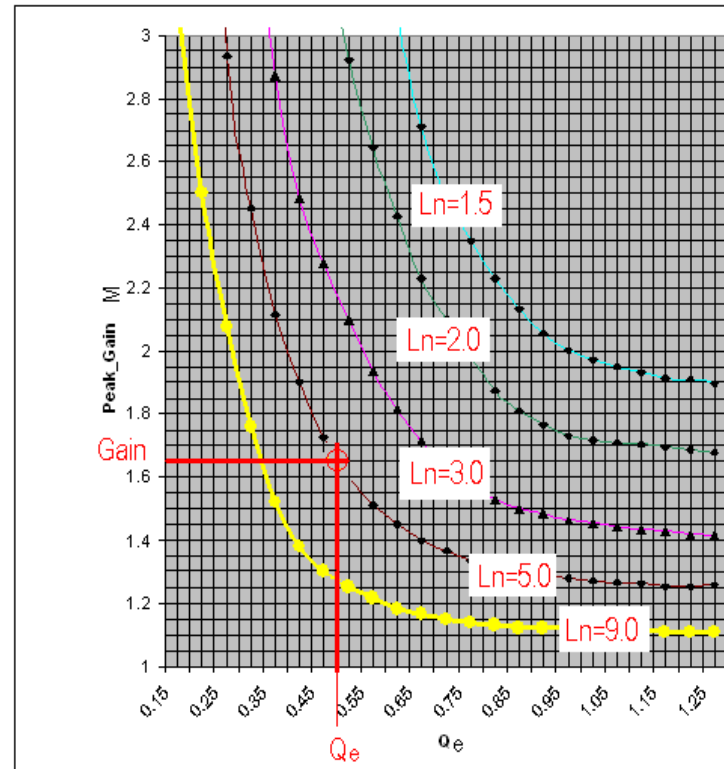
➤ Larger magnetizing current
➤ Larger turn off loss

Trade-off Design of Dead Time



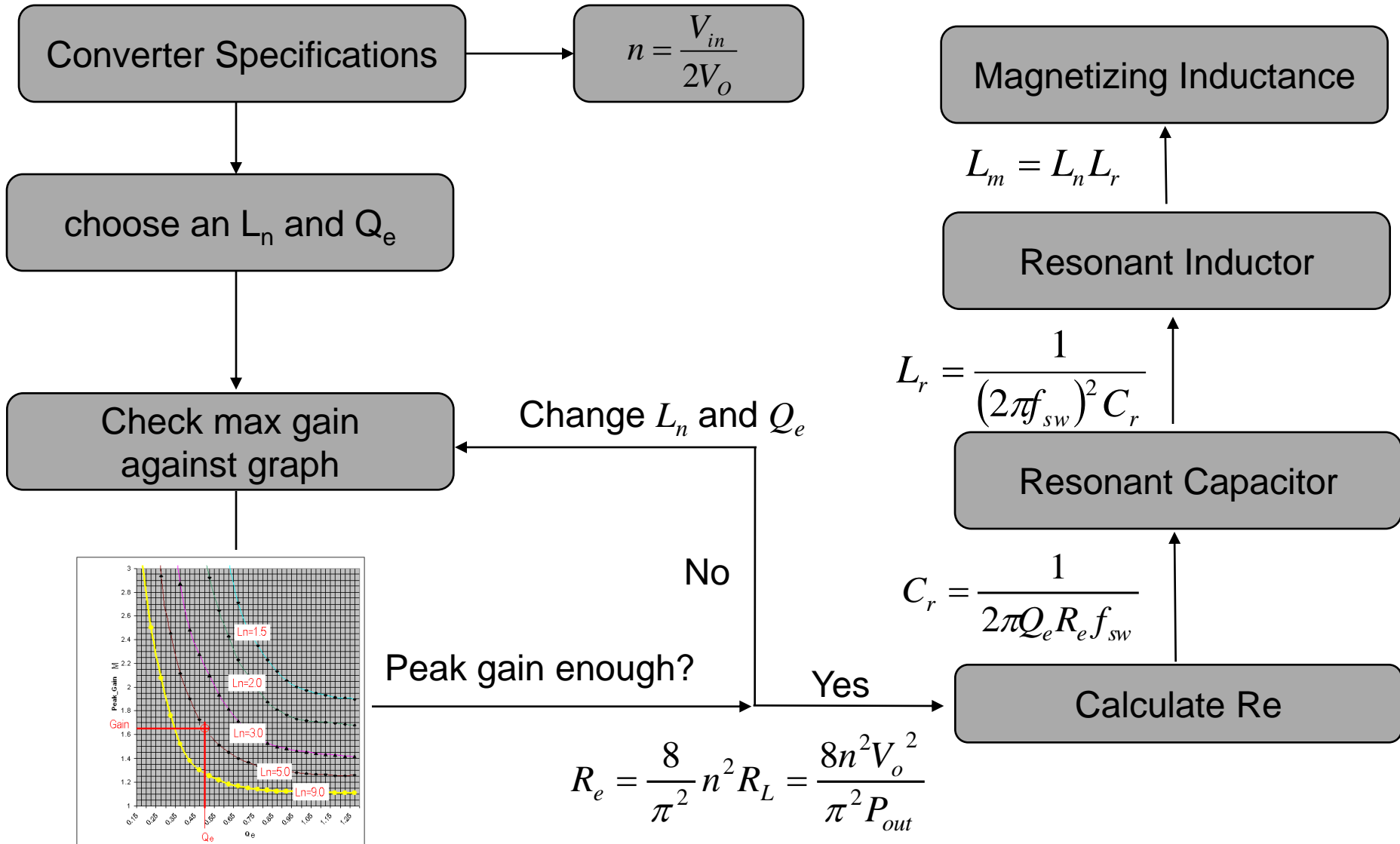
➤ Trade-off between the switching loss and conduction loss on a case of 100ns dead time

Peak Gains with Ln and Qe

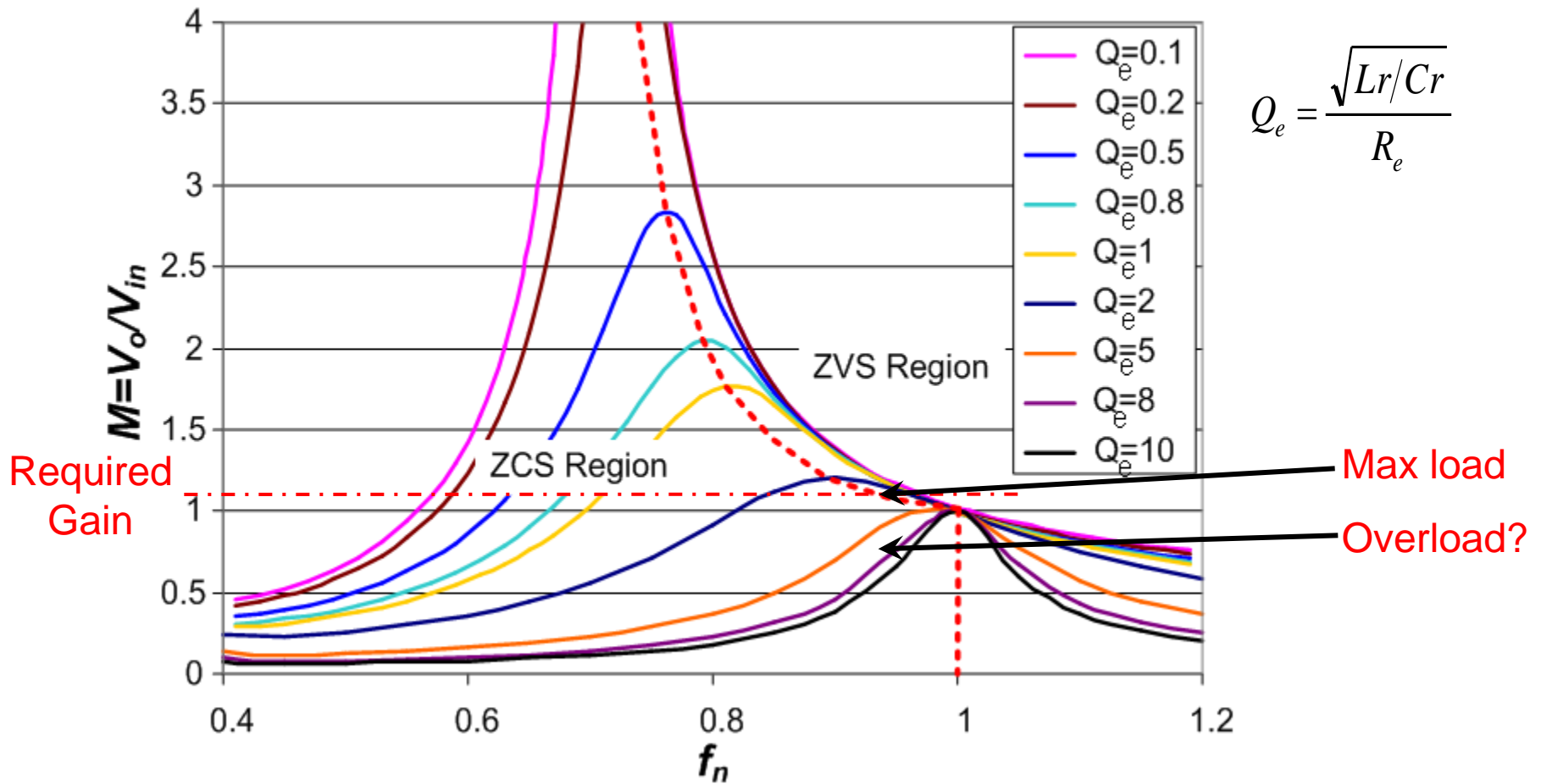


- Initially select L_n in the range of 3 to 5 (gain curve not very flat and able to narrow down the frequency change while there is still enough gain)
- Find proper Q_e to get enough peak gain

Design Flow Chart for LLC Resonant Converter

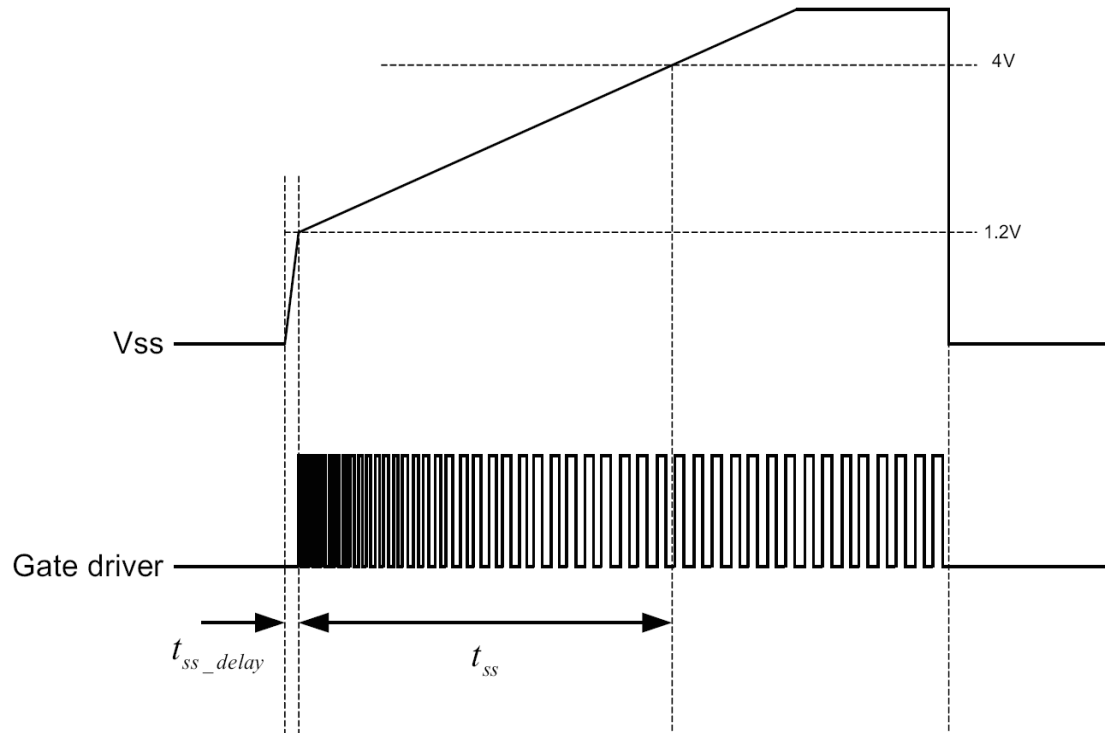


Design - Over Current Protection



➤ During over load condition, check if the converter enters ZCS region

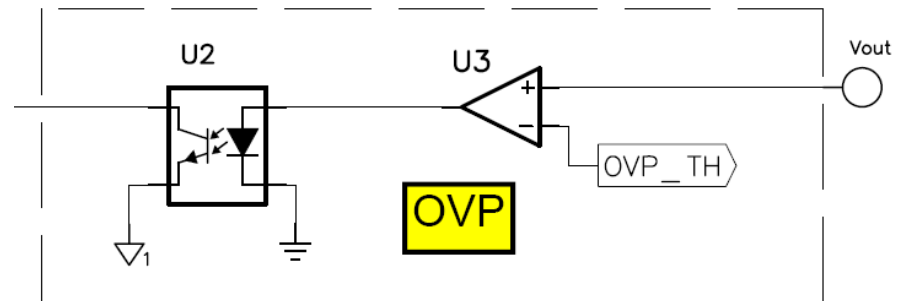
Design - *Soft start*



- Soft start is achieved by frequency control

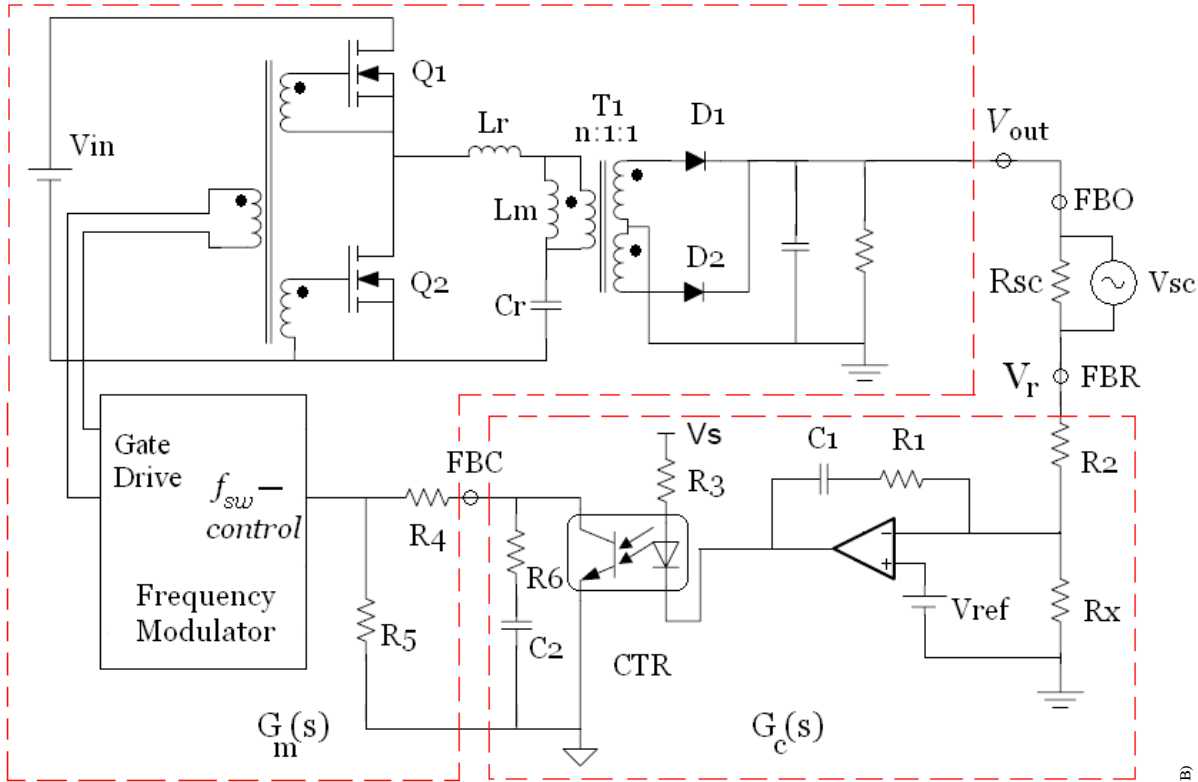
Design – OVP and Burst Operation

- Secondary OVP
 - Feedback loop fault may cause output over voltage.
 - Slow loop response may also cause OVP.
 - Independent OVP circuit is needed.

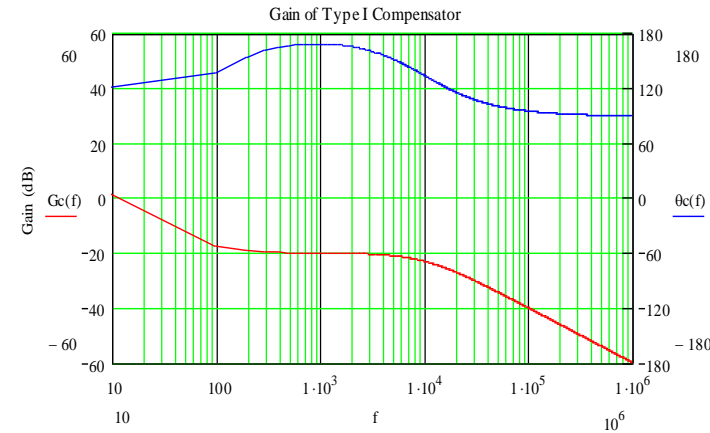
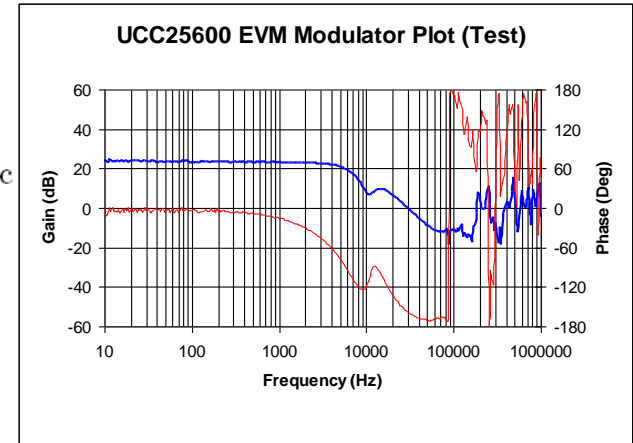


- Burst Operation
 - To cover no load operation, smaller L_n is needed which increases circulating (magnetizing) current, leading more conduction losses.
 - To reduce switching losses, ZVS is still needed at no load. This requires higher magnetizing current, too.
 - To maintain output regulation, burst operation at light load and no load is an alternative to balance switching losses and conduction losses.

Feedback Loop Design



$$G_c(S) = K_{dc} \frac{\frac{S}{C1 \times R2} + 1}{S \times \left(\frac{k_{opto} S}{2\pi \times f_{p_opto}} + 1 \right)}$$



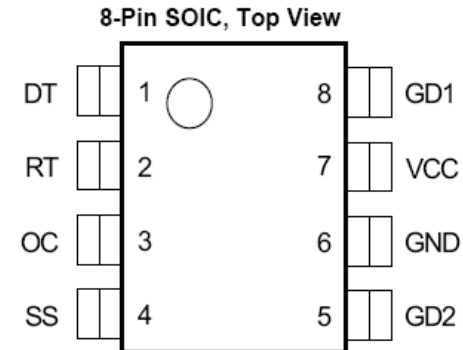
- Measure $G_m(j\omega)$
- Design $G_c(j\omega)$ based on $G_m(j\omega)$ measurement

Summary

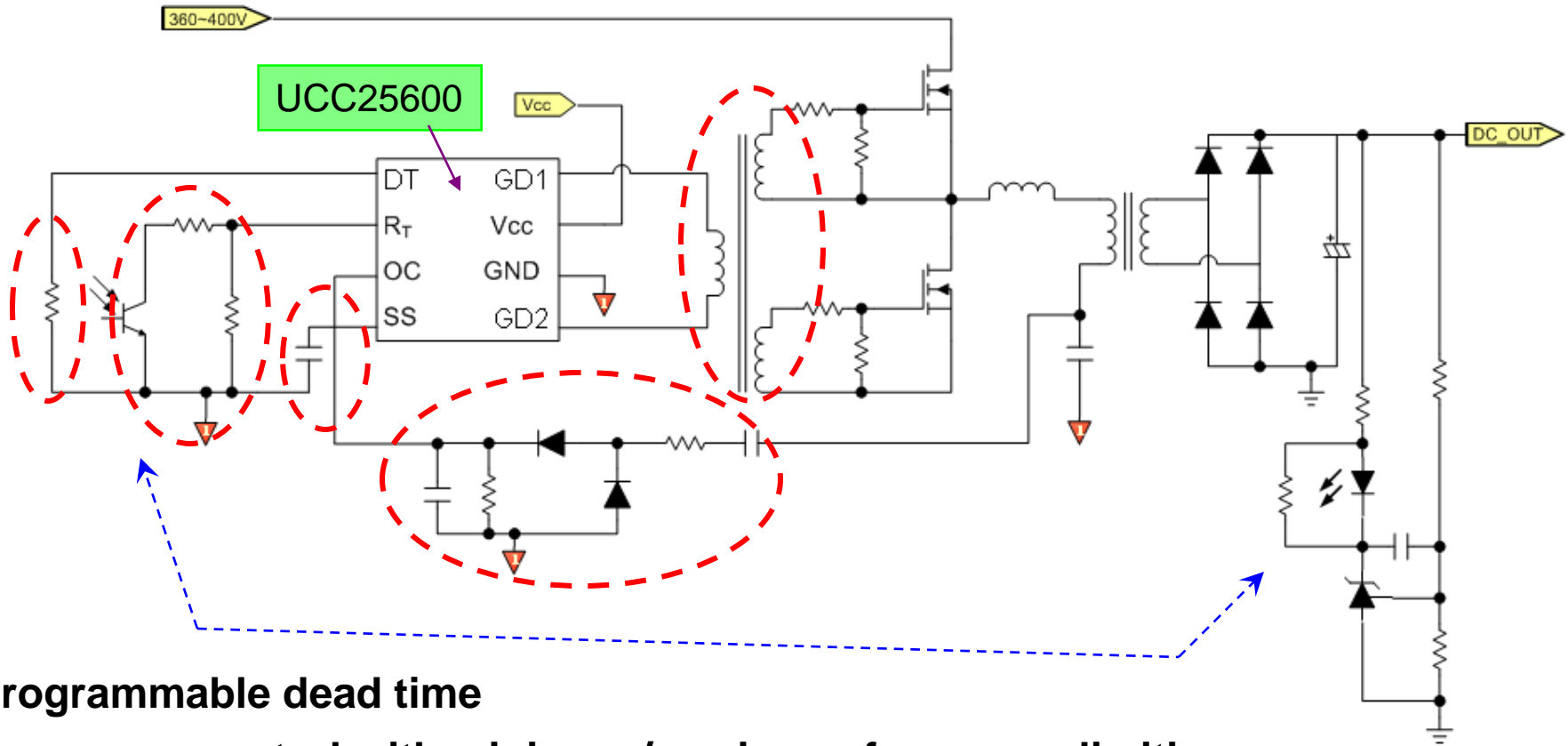
- LLC resonant converter is able to achieve wide operation together with high efficiency
- Due to low switching losses, LLC resonant converter is able to operate at high switching frequencies, while maintaining high efficiency
- LLC resonant converter design needs to find a suitable magnetizing inductor to ensure small conduction losses and switching losses
- By choosing a suitable L_n and Q_e value, desired voltage gain can be achieved to input and output voltage variation range

UCC25600 Resonant Half Bridge Controller

- Complete system features
 - Programmable soft start
 - Programmable dead time
 - Programmable maximum/minimum switching frequency
 - 0.4A source, 0.8A sink driving capability
 - Simple ON/OFF control
 - Burst operation at light load condition
- Precise timing control
 - 3% accuracy on minimum switching frequency setting with only external resistor
 - $\pm 50\text{ns}$ matching on dead time
 - Soft start timer range from 1ms to 500ms
- Complete protection functions
 - Two levels over current protection, auto recovery and latch off
 - Bias voltage UVLO and OV protection
 - Over temperature protection
 - Soft start enabled after all fault conditions
- 8 pin SOIC package, simplifies design and layout



Application Circuit



Programmable dead time

Frequency control with minimum/maximum frequency limiting

Programmable soft start with on/off control

Two level over current protection, auto-recovery and latch up

Matching output with 50ns tolerance

Test based on EVM (UCC25600EVM)

Table 1. UCC25600EVM Electrical Performance Specifications

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------------|---|------|-------|------|----------|
| Input Characteristics | | | | | |
| Voltage range | V_{IN} | 375 | 390 | 405 | V_{DC} |
| Maximum input current | $V_{IN} = 390 V_{DC}$, $I_{OUT} = 25A$ | | | 0.88 | A |
| Switching frequency | $V_{IN} = 390 V_{DC}$, $I_{OUT} = 25A$ | | 110 | | kHz |
| Output Characteristics | | | | | |
| Output voltage V_{OUT} | $V_{IN}: 390 V_{DC}$, $I_{OUT}: 1A$ | 11.9 | 12 | 12.2 | V_{DC} |
| Load current ⁽¹⁾ | $V_{IN}: 390 V_{DC}$ | 0 | | 25 | A |
| Continuous output power | $V_{IN}: 390 V_{DC}$ | | | 300 | W |
| Line regulation | $V_{IN}: 375 V_{DC}$ to $405 V_{DC}$, $I_{OUT} = 1.0A$ | | | 5 | mV |
| Load regulation | $V_{IN}: 390 V_{DC}$, $I_{OUT}: 1 - 25A$ | | | 50 | |
| Load starting burst ⁽¹⁾ | $V_{IN}: 390 V_{DC}$ | | 0.5 | | A |
| Ripple and noise (20 MHz BW) | $V_{IN}: 390 V_{DC}$, $I_{OUT} = 25A$ | | | 120 | mVpk-pk |
| Over current threshold, I_{o_ocp} | $V_{IN}: 390 V_{DC}$ | | 30 | | A |
| Max power limit | $V_{IN}: 390 V_{DC}$ | | 350 | | W |
| Efficiency | | | | | |
| Peak | $V_{IN} = 390 V_{DC}$, $I_{OUT} = 15 A$ | | 92.5% | | |
| Full load | $V_{IN} = 390 V_{DC}$, $I_{OUT} = 25 A$ | | 91% | | |
| Operation ambient temperature | Full load, forced air cooling 400 LFM | | | 45 | C |

⁽¹⁾ The EVM output may present saw-tooth waveforms or a voltage higher than the regulation point typically about 13.1 V depending on load levels and the speed when the load is reduced. The saw-tooth waveform is caused by UCC25600 burst operation. The output voltage of 13.1 V is caused by output over voltage protection.

Test with EVM: Resonant Tank

- Ch3: Lr Current
 - Scale: 3.4A/div
- Primary Peak Current: 2.72A
- Secondary Peak Current (Nt=16.7):
 - $3.4\text{A/div} \times 0.8\text{div} \times 16.7 = 45.4\text{A}$
- Load Current: 25A
 - $I_o/I_s = 25/45.4 = 0.55$
 - Compare: half wave rectifier

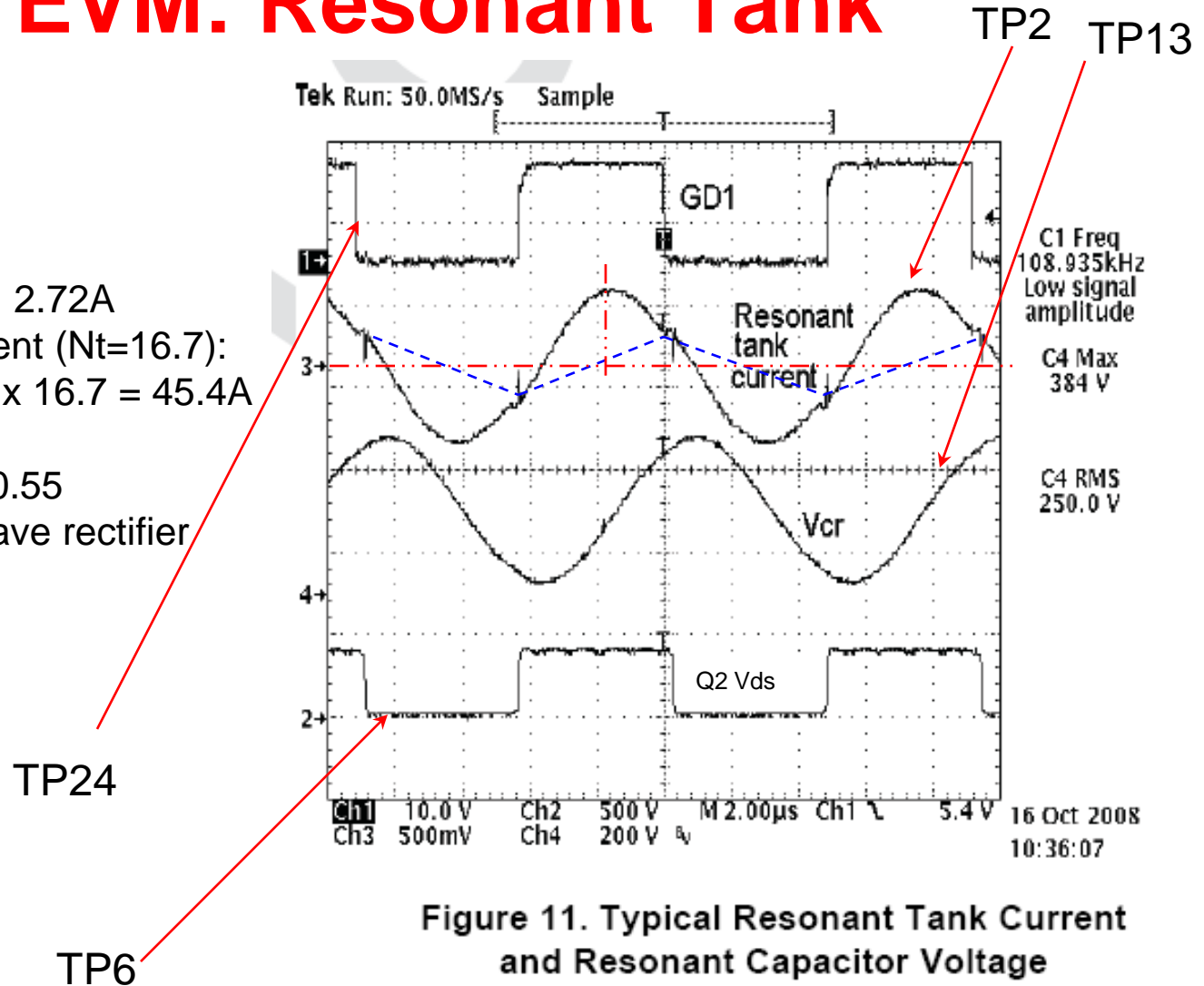


Figure 11. Typical Resonant Tank Current and Resonant Capacitor Voltage

Test with EVM: Ripple and Hiccup

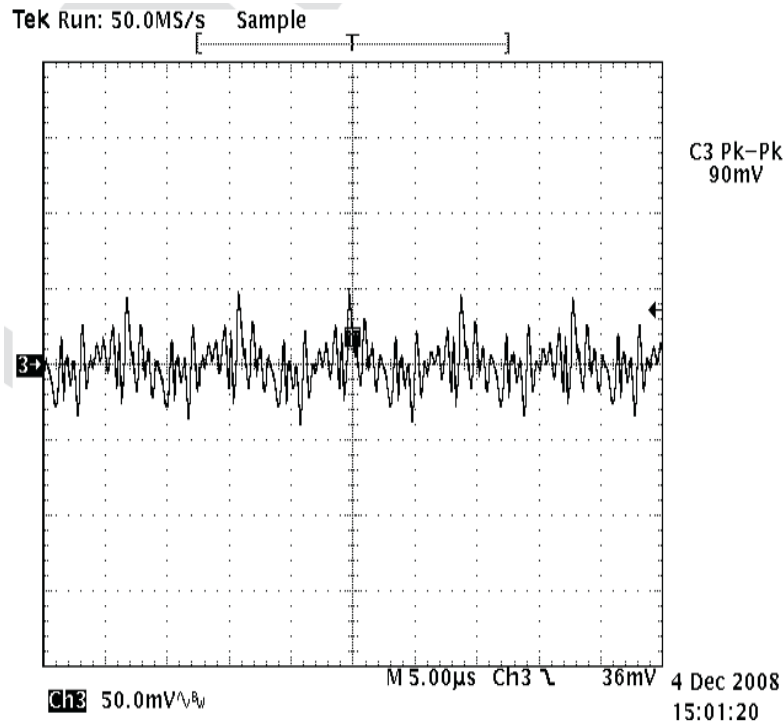


Figure 7. Typical Output Voltage Ripple Waveform at $V_{IN} = 390\text{ V}$ and $I_O = 15\text{ A}$ (TP15)

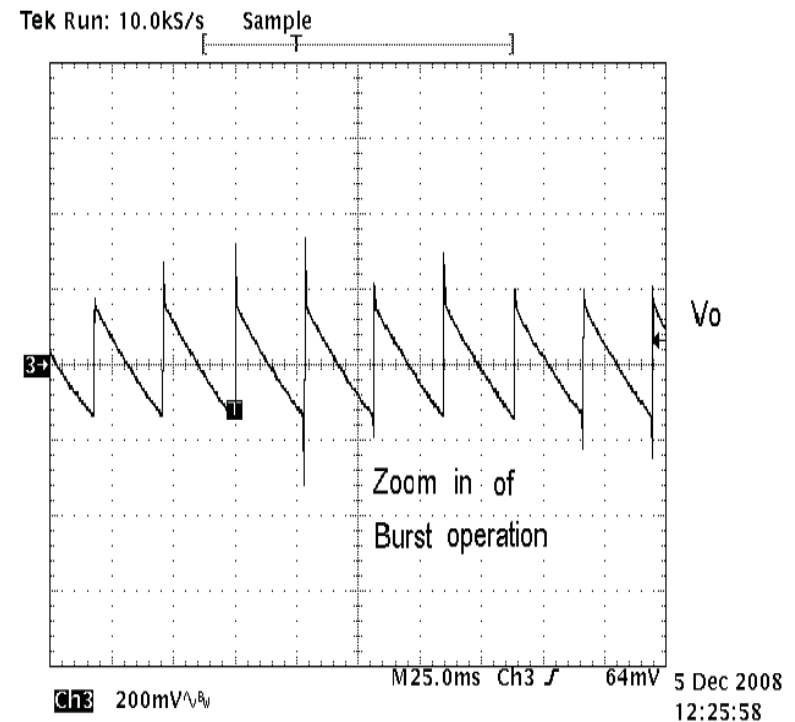
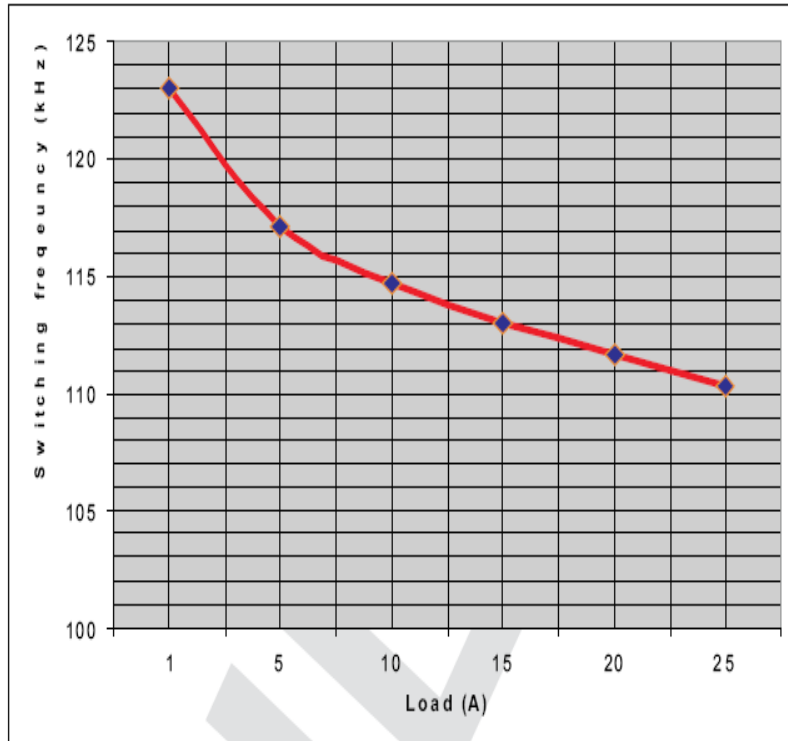
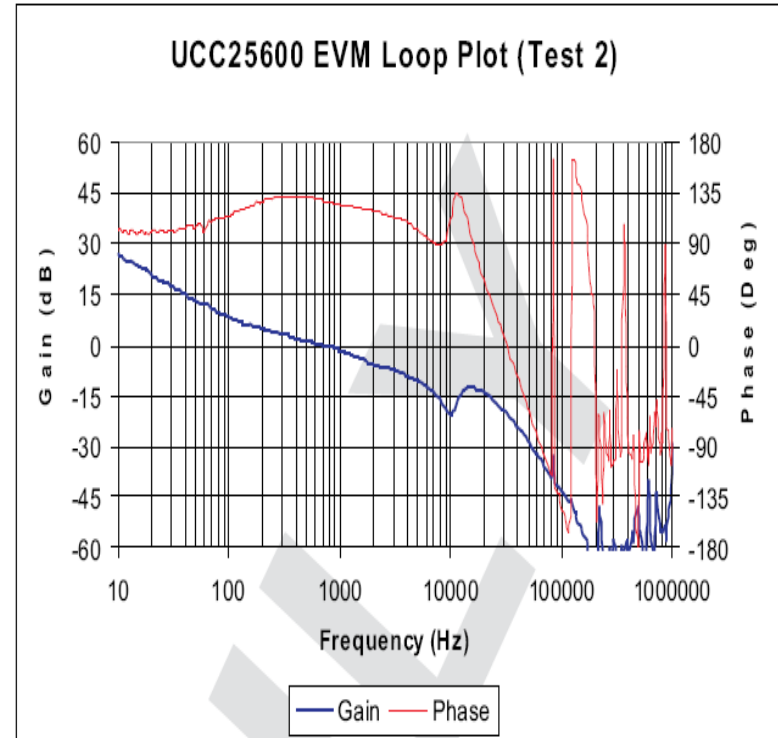


Figure 16. Typical Output Voltage in Burst Operation (TP15)

Test with EVM: Freq and Feedback

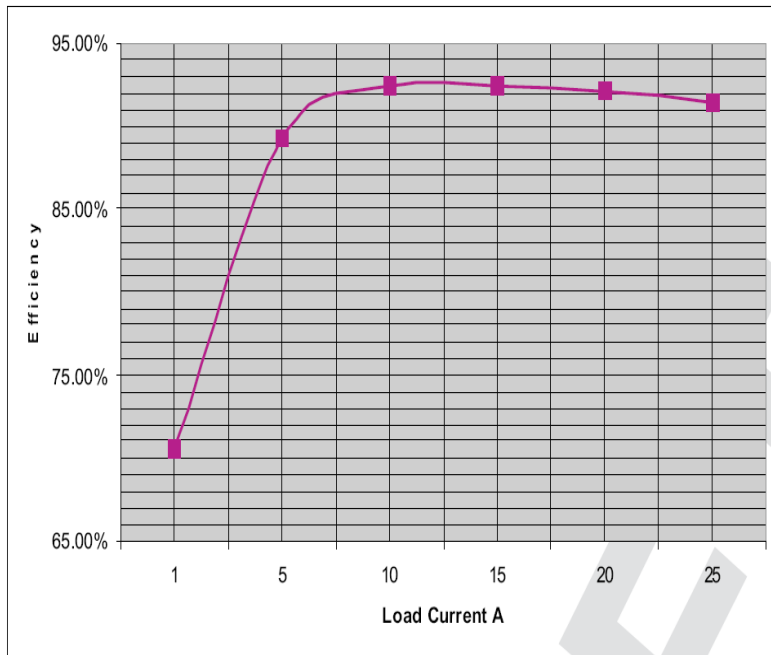


Frequency Variation

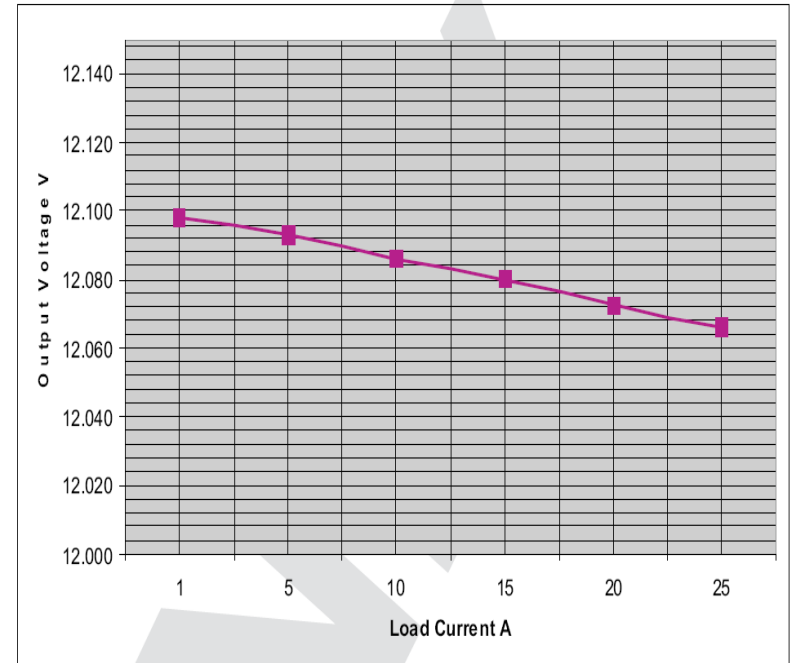


Feedback Loop Bode Plots

Test with EVM: Efficiency and Load Regulation



Efficiency



Load Regulation

Thank You!